JAYPEE UNIVERSITY OF INFORMATION TECHNOLOGY, WAKNAGHAT TEST -2 EXAMINATION- May 2023

M.Tech. CSE/IT 2nd Semester

COURSE CODE: 22M1WCI235

MAX. MARKS: 25

COURSE NAME: REINFORCEMENT LEARNING

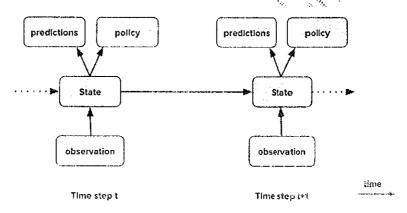
COURSE CREDITS: 03

MAX. TIME: 1.5Hr

COURSE COORRDINATOR: Prof (Dr.) Vivek Kumar Sehgal

Note: All questions are compulsory. Carrying of mobile phone during examinations will be treated as case of unfair means.

1. Among the following agent components what is the role of?



- a. Agent State
- b. Policy
- c. Value functions
- d. Model

How is the history used to construct the agent state S_t ?

CO-1 [5]

2. (a) Explain the following mathematical framework for Markov decision processes.

$$p(r, s | S_t, A_t) = p(r, s | \mathcal{H}_t, A_t)$$
 CO-2 [2.5]

(b) What is the difference between Fully Observable Environments and Partially Observable Environments?

CO- 2 [2.5]

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- 3. What is the role of value function in Reinforcement learning? Write the value function for:
 - Actual value function in the form of $v_{\pi}(s)$ including discount factor $\gamma[0,1]$
 - Value Function using Bellman equation.

CO-3 [5]

4. (a) Explain the following model which predicts what the environment will do next;

$$\mathcal{P}(s,a,s') \approx p(S_{t+1} = s' \mid S_t = s, A_t = a)$$

CO- 3 (2.5)

- (b) Differentiate the following agent categories:
 - i. Value Based
 - ii. Policy Based
 - iii. Actor Critic

CO-3 [2.5]

- 5. (a) What is the role of Prediction and Control for a given policy? How these can be strongly related?

 CO- 3 [2.5]
 - (b) Explain the following Learning Agent Components:
 - Policies: $\pi: \mathcal{S} \to \mathcal{A}$ (or to probabilities over \mathcal{A})
 - Value functions: $v: \mathcal{S} \to \mathbb{R}$
 - Models: $m: S \to S$ and/or $r: S \to \mathbb{R}$
 - -State update: $u: \mathcal{S} \times \mathcal{O} \rightarrow \mathcal{S}$

CO-3 [2.5]