

JAYPEE UNIVERSITY OF INFORMATION TECHNOLOGY, WAKNAGHAT

TEST -3 EXAMINATION- 2025

B.Tech-III Semester (ECE)

COURSE CODE (CREDITS): 25B11EC311 (4)

MAX. MARKS: 35

COURSE NAME: Signals and Systems

COURSE INSTRUCTORS: Dr. Vikas Baghel

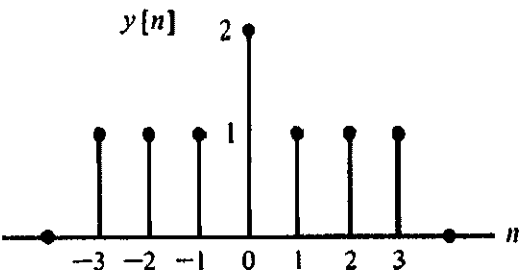
MAX. TIME: 2 Hours

**Note:** (a) All questions are compulsory.

(b) The candidate is allowed to make Suitable numeric assumptions wherever required for solving problems

(c) Use of a standard scientific calculator is allowed.

Q.No	Question	CO	Marks
Q1	<p>a) Show that</p> $\left[2^{-n} \cos\left(\frac{\pi}{3}n\right)\right] u[n-1] \Leftrightarrow \frac{0.25(z-1)}{z^2 - 0.5z + 0.25}$ <p>b) By expanding <math>X[z] = \frac{yz}{(z-\gamma)^2}</math> as a power series in <math>z^{-1}</math>, show that <math>x[n] = n\gamma^n u[n]</math>.</p> <p>c) Find the output <math>y[n]</math> of an LTID system:</p> $2y[n+2] - 3y[n+1] + y[n] = 4x[n+2] - 3x[n+1]$ <p>given <math>y[-1] = 0</math>, <math>y[-2] = 1</math>, and <math>x[n] = 4^{-n} u[n]</math>.</p>	[CO4]	[3]
Q2	<p>a) For each of the systems specified by the following transfer functions, find the differential equation relating the output <math>y(t)</math> to the input <math>x(t)</math>: <math>H(s) = (s+5)/(s^2+3s+8)</math>.</p> <p>b) For an LTIC system with zero initial conditions, if an input <math>x(t)</math> produces an output <math>y(t)</math>, then show that:</p> <ol style="list-style-type: none"> <li>The input <math>\frac{dx(t)}{dt}</math> produces an output <math>\frac{dy(t)}{dt}</math>,</li> <li>The input <math>\int_0^t x(\tau)d\tau</math> produces an output <math>\int_0^t y(\tau)d\tau</math>.</li> <li>Hence, show that the unit step response of a system is an integral of the impulse response; that is <math>\int_0^t h(\tau)d\tau</math>.</li> </ol> <p>c) Derive the Initial Value Theorem (IVT) for the Laplace Transform.</p>	[CO4]	[2]
			[3]

<b>Q3</b>	<p>a) Consider the signal <math>y[n]</math> in figure. Find the signal <math>x[n]</math> such that <math>Even\{x[n]\} = y[n]</math> for <math>n \geq 0</math> and <math>Odd\{x[n]\} = y[n]</math> for <math>n &lt; 0</math>.</p>  <p>b) Find the FS coefficients of signal</p> $x(t) = [1 + \cos(2\pi t)] \sin\left(10\pi t + \frac{\pi}{6}\right)$ <p>Also plot the magnitude and the phase spectrum.</p> <p>c) Consider the discrete time system described by the difference equation</p> $y[n] = \sum_{k=-\infty}^n (-1)^{n-k} x[k]$ <p>Find out its impulse response <math>h[n]</math> and frequency response <math>H(\Omega)</math>.</p>	<p>[CO3]</p>	<p>[3]</p>
<b>Q4</b>	<p>a) Derive the cutoff frequency of a first-order RC high-pass filter.</p> <p>b) A low-pass RC filter has <math>R = 1 \text{ k}\Omega</math> and <math>C = 0.1 \mu\text{F}</math>.</p> <ol style="list-style-type: none"> <li>Compute the cutoff frequency <math>f_c</math>.</li> <li>For a <math>1 \text{ V}_{rms}</math> input at <math>f = f_c</math>, compute the output amplitude using <math>-3 \text{ dB}</math> definition.</li> </ol> <p>c) Draw the signal-flow structure of given IIR filter:</p> $y[n] = 1.2y[n-1] - 0.36y[n-2] + x[n] + 0.5x[n-1]$ <p>Also find whether this filter is stable or not.</p>	<p>[CO1]</p>	<p>[3]</p>